

EPOS – European Plate Observing System

# Near-real time estimation of troposphere delay and deformations

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**European  
Funds**  
Smart Growth



**Republic  
of Poland**

**European Union**  
European Regional  
Development Fund



# EPOS - European Plate Observing System

POIR.04.02.00-14-A0003/16

Priority IV: INCREASING THE RESEARCH POTENTIAL

Action 4.2: DEVELOPMENT OF MODERN RESEARCH INFRASTRUCTURE OF THE SCIENCE SECTOR

Period of realization: 2016 - 2021

Project value: 61 996 279,64 PLN

ERDF co-financing: 46 632 332,69 PLN

Beneficiary:



Instytut Geofizyki  
Polskiej Akademii Nauk

Consortium members:

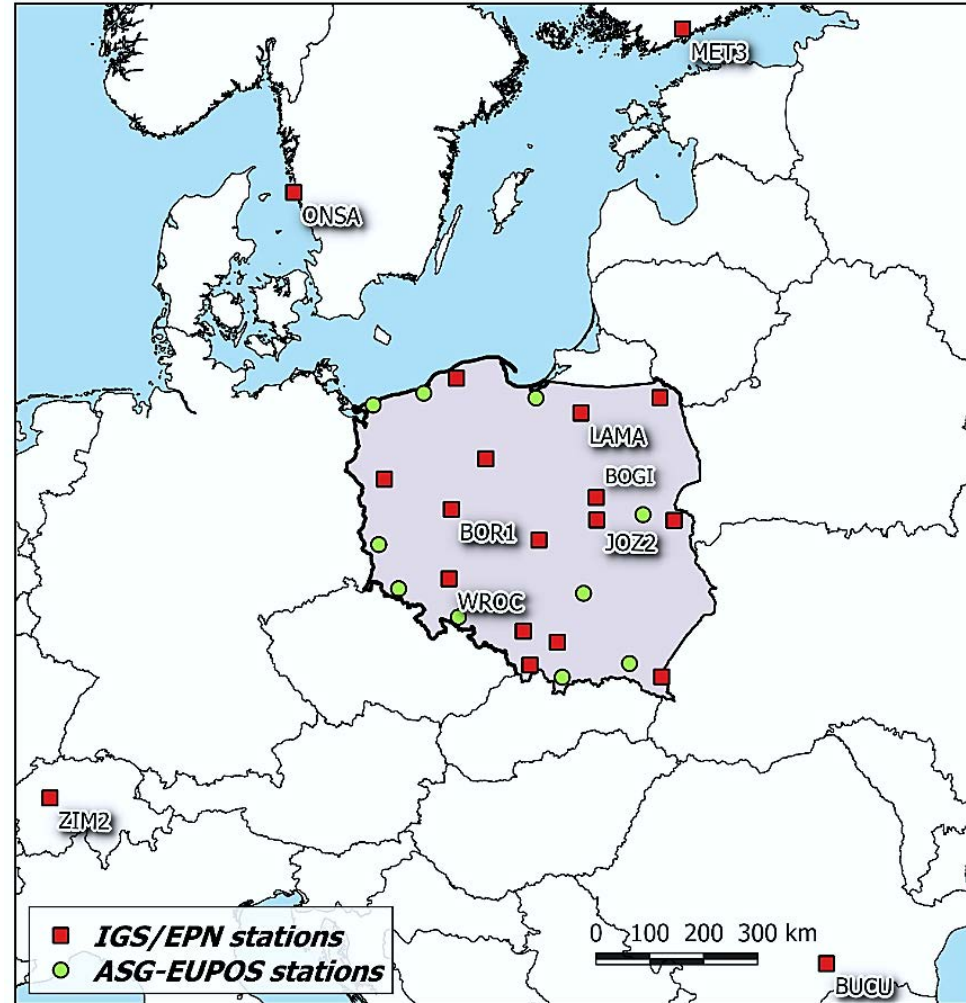


PROJECT EPOS - EUROPEAN PLATE OBSERVING SYSTEM IS CO-FINANCED BY THE EUROPEAN UNION FROM THE FUNDS OF THE EUROPEAN REGIONAL DEVELOPMENT FUND (ERDF)



# Troposphere test goals

- ❑ Upgrade NRT 1h processing to **Ultra - fast NRT 15-minutes**
- ❑ Use the ultra-fast scenario to monitor troposphere parameters
- ❑ Achieve satisfactory quality of products

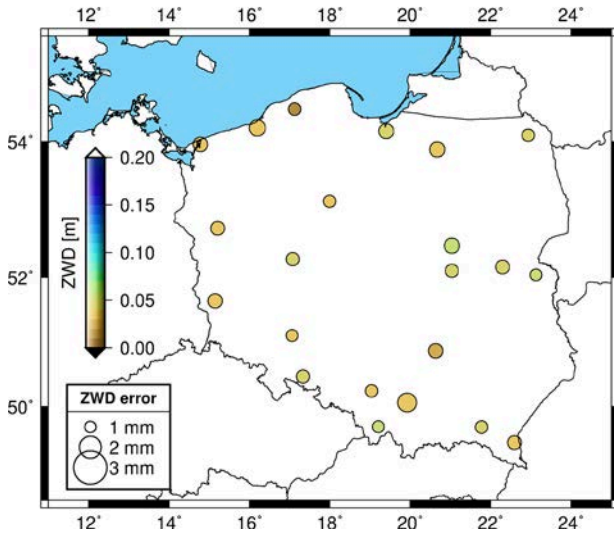


GNSS network for ultra-fast NRT tests

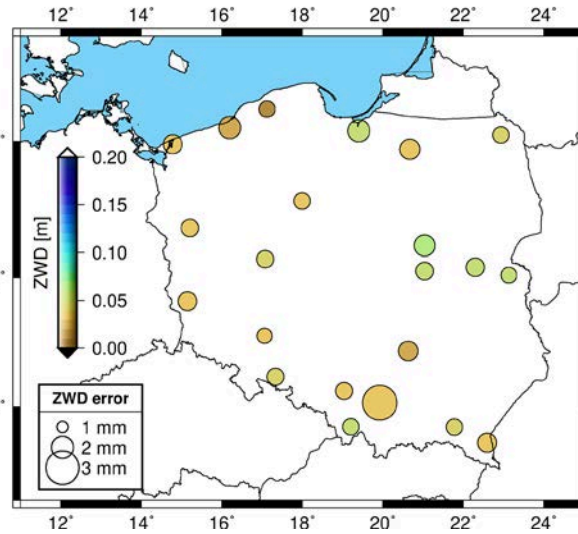


# ZWD Variations

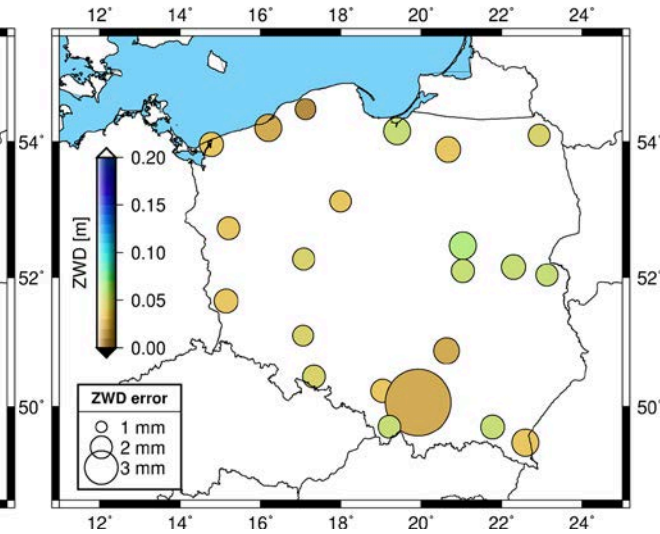
ZWD VARIATIONS AT 2018 069 00h 00min UTC



ZWD VARIATIONS AT 2018 069 00h 00min UTC



ZWD VARIATIONS AT 2018 069 00h 00min UTC



		Ultra-fast processing			Daily processing
		Maximum ZTD / Grad.	Medium ZTD / Grad.	Minimum ZTD / Grad.	Reference ZTD / Grad.
MF	Constraining				
	Niell	1.0 / 0.1 mm	2.5 / 0.25 mm	10.0 / 1.0 m	-----
	GMF	1.0 / 0.1 mm	2.5 / 0.25 mm	10.0 / 1.0 mm	-----
	VMF1	1.0 / 0.1 mm	2.5 / 0.25 mm	10.0 / 1.0 mm	1 m / 1m



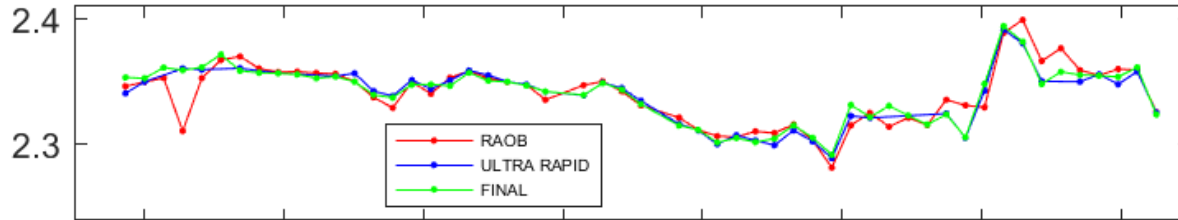
Bernese GNSS Software  
Version 5.2



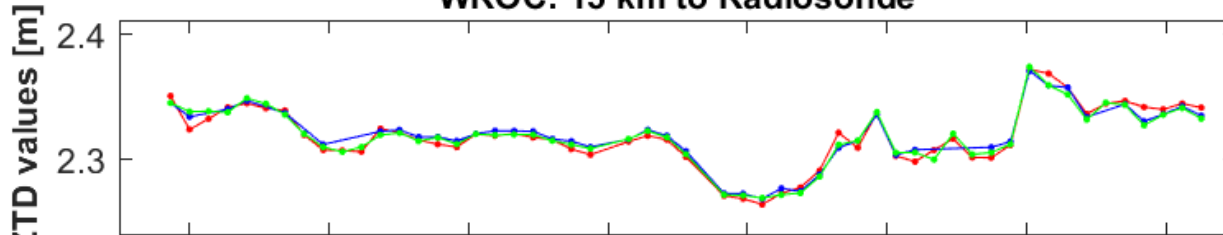


# Radiosonde vs. NRT: ZTD comparison

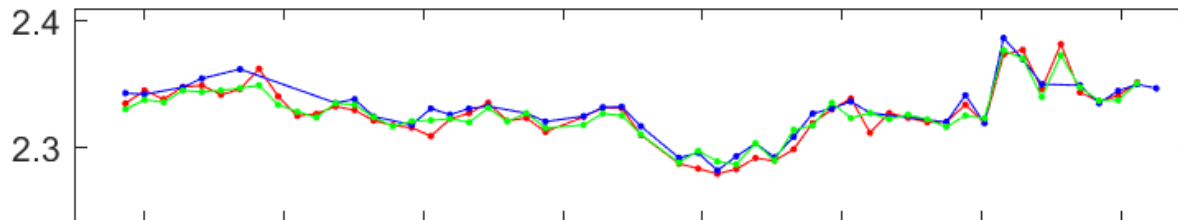
### REDZ: 50 km to Radiosonde



### WROC: 15 km to Radiosonde

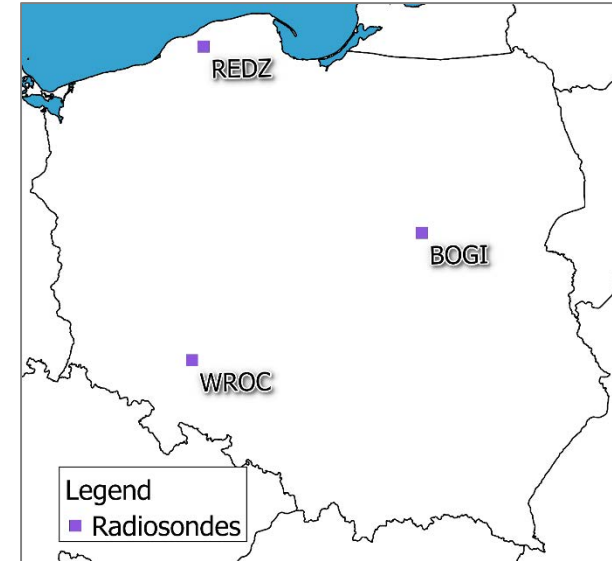


### BOGI: 12 km to Radiosonde



2018.13 2018.14 2018.15 2018.16 2018.17 2018.18 2018.19 2018.2

Part of the year

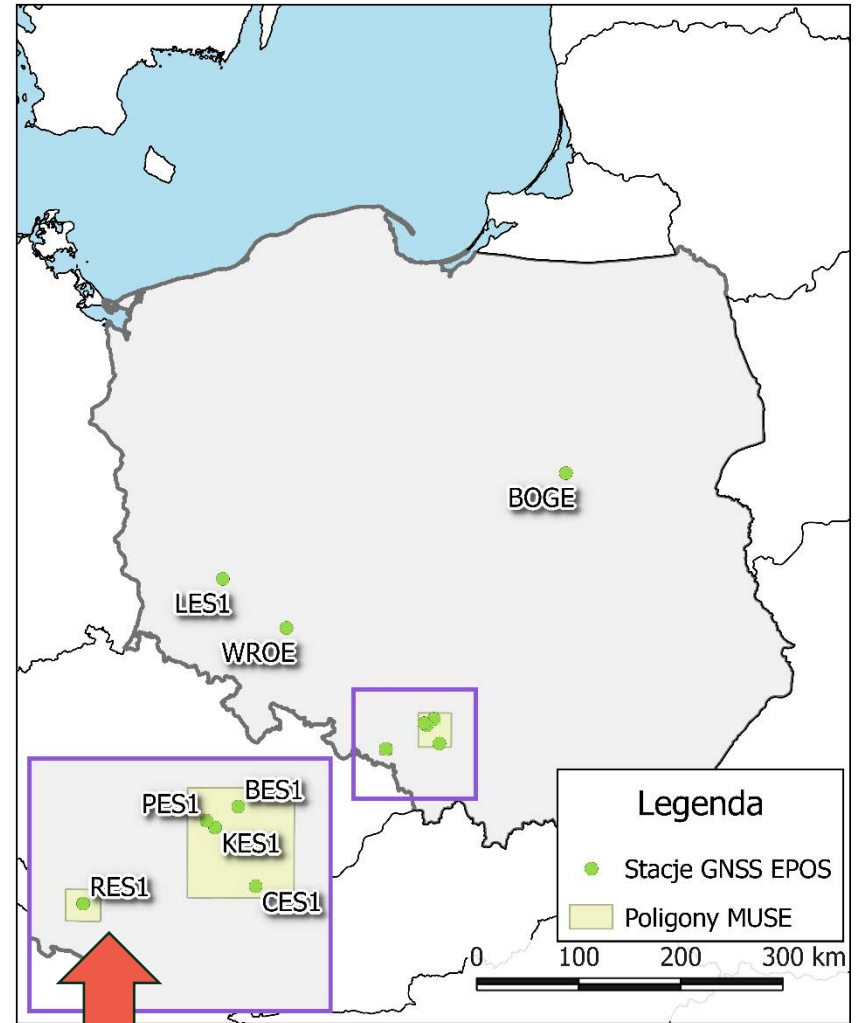
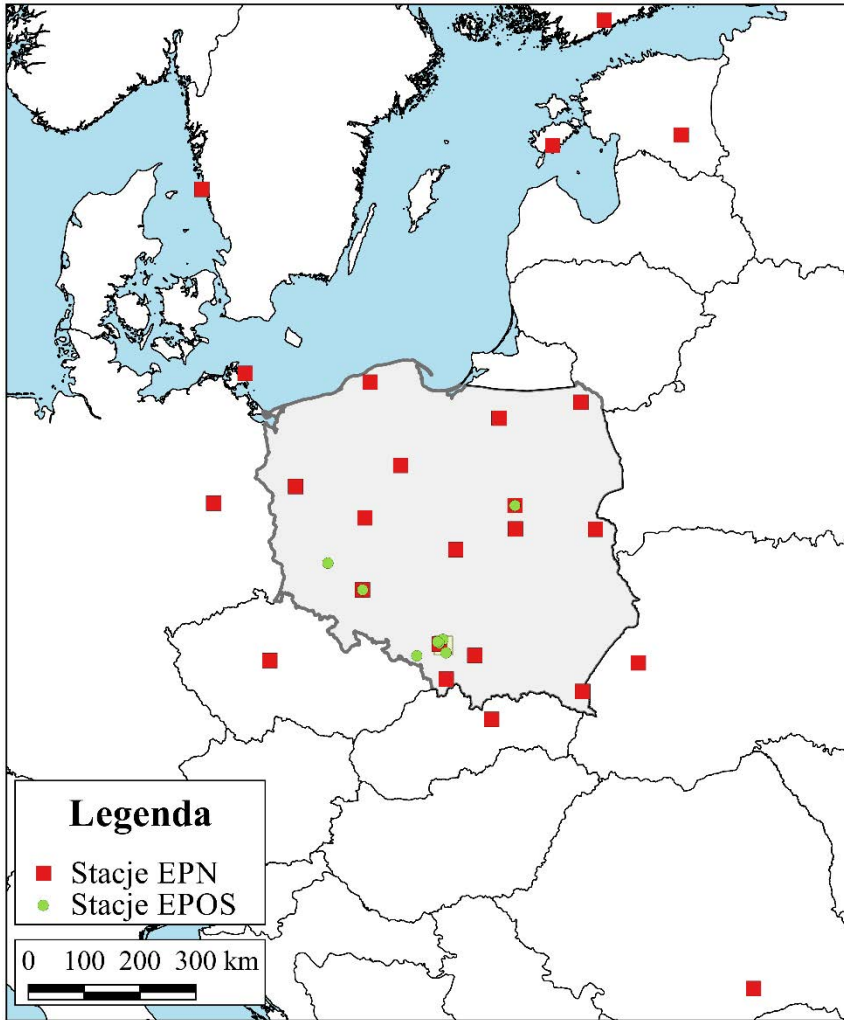


## Mean Std. of ZTD

- Radiosonde vs. Ultra-fast: **7.4 mm** (For VMF1 and Max. constaining)
- Radiosonde vs Final: **7.5 mm**



# GNSS EPOS Stations in NRT solution





# The RES1 station





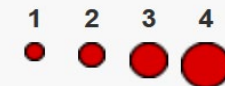
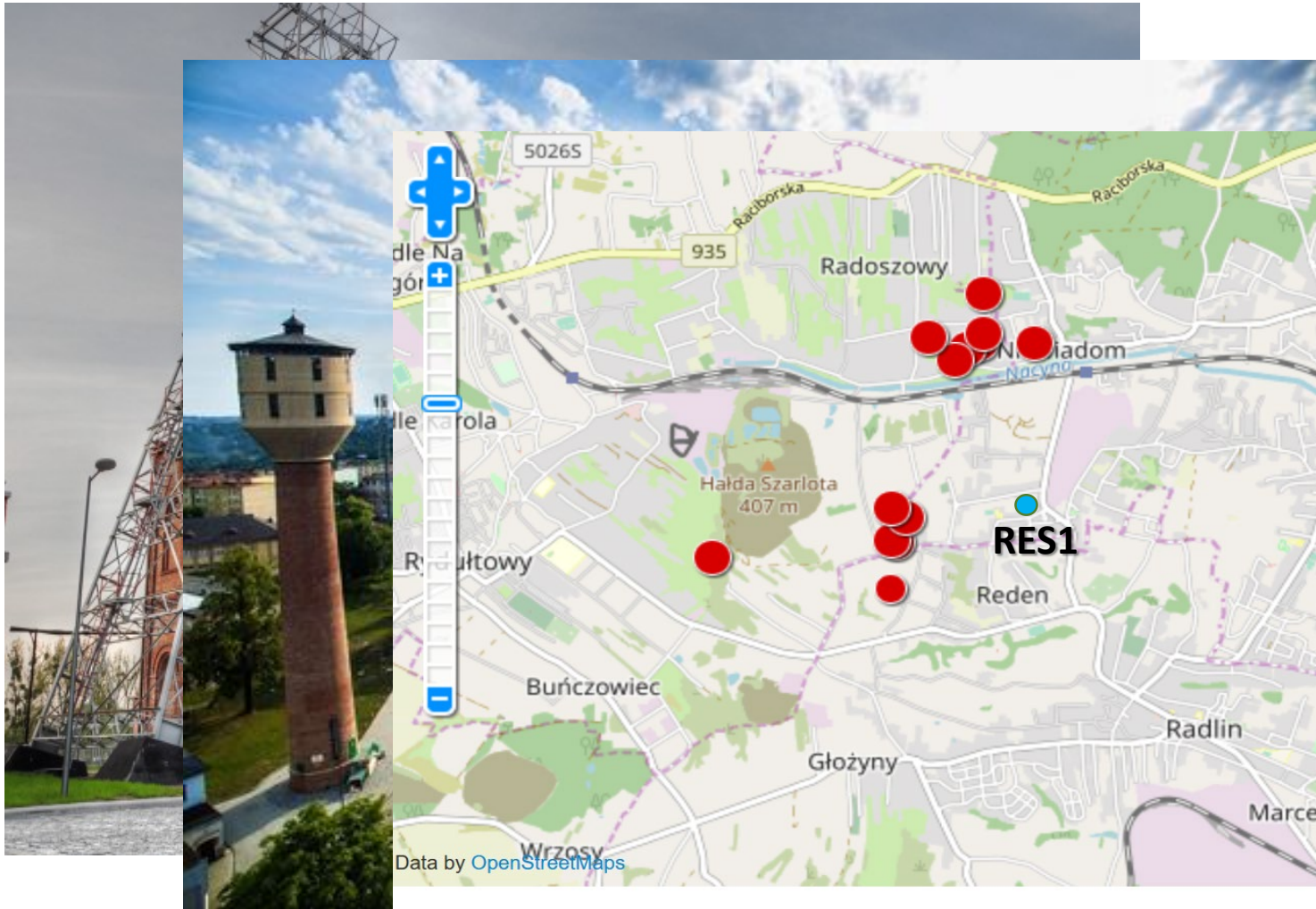
# The RES1 station

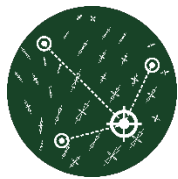




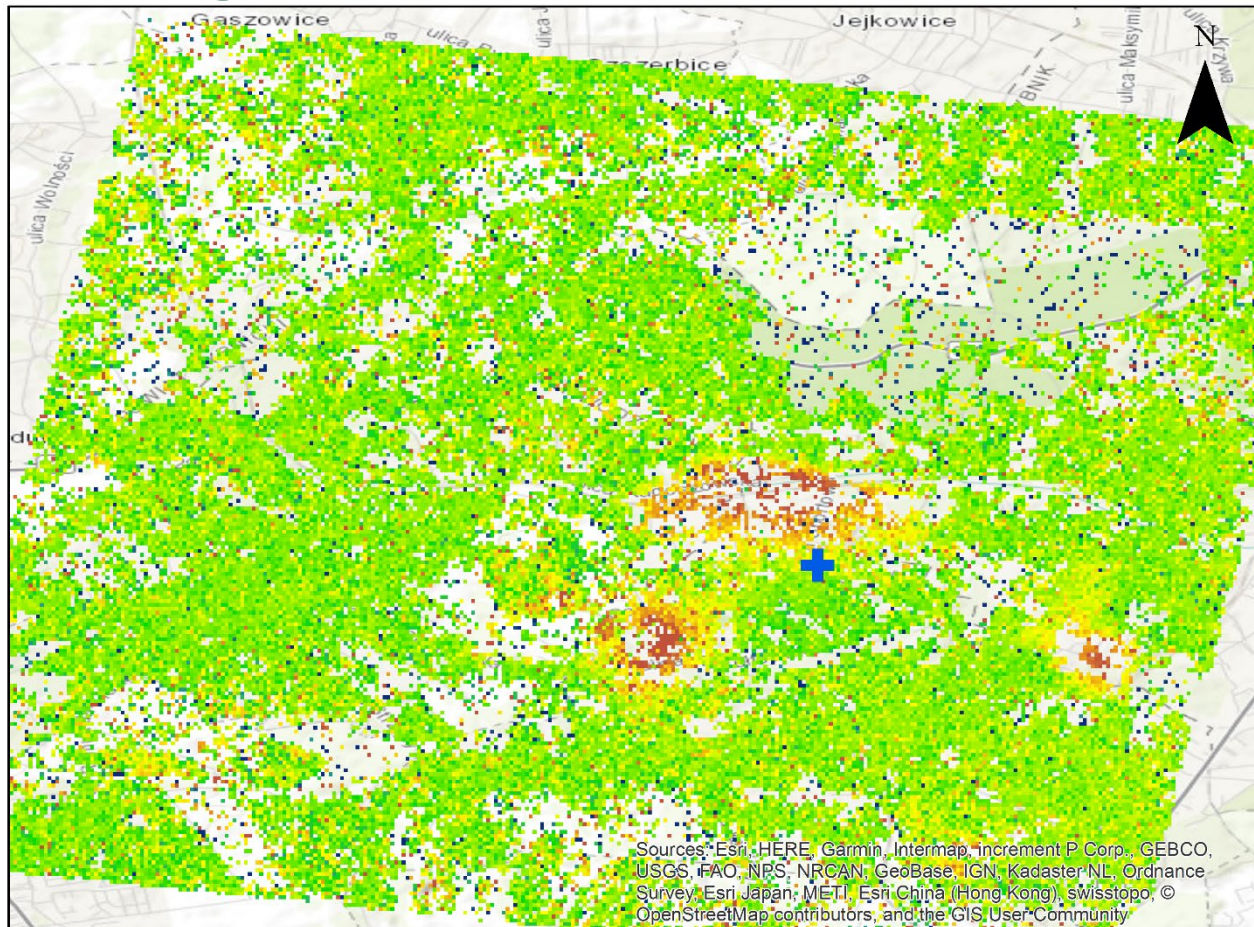


# The RES1 station





# Mining deformation of PInSAR



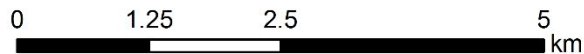
+ GNSS Station

Deformation estimated using PInSAR

High : 303.504 [mm]



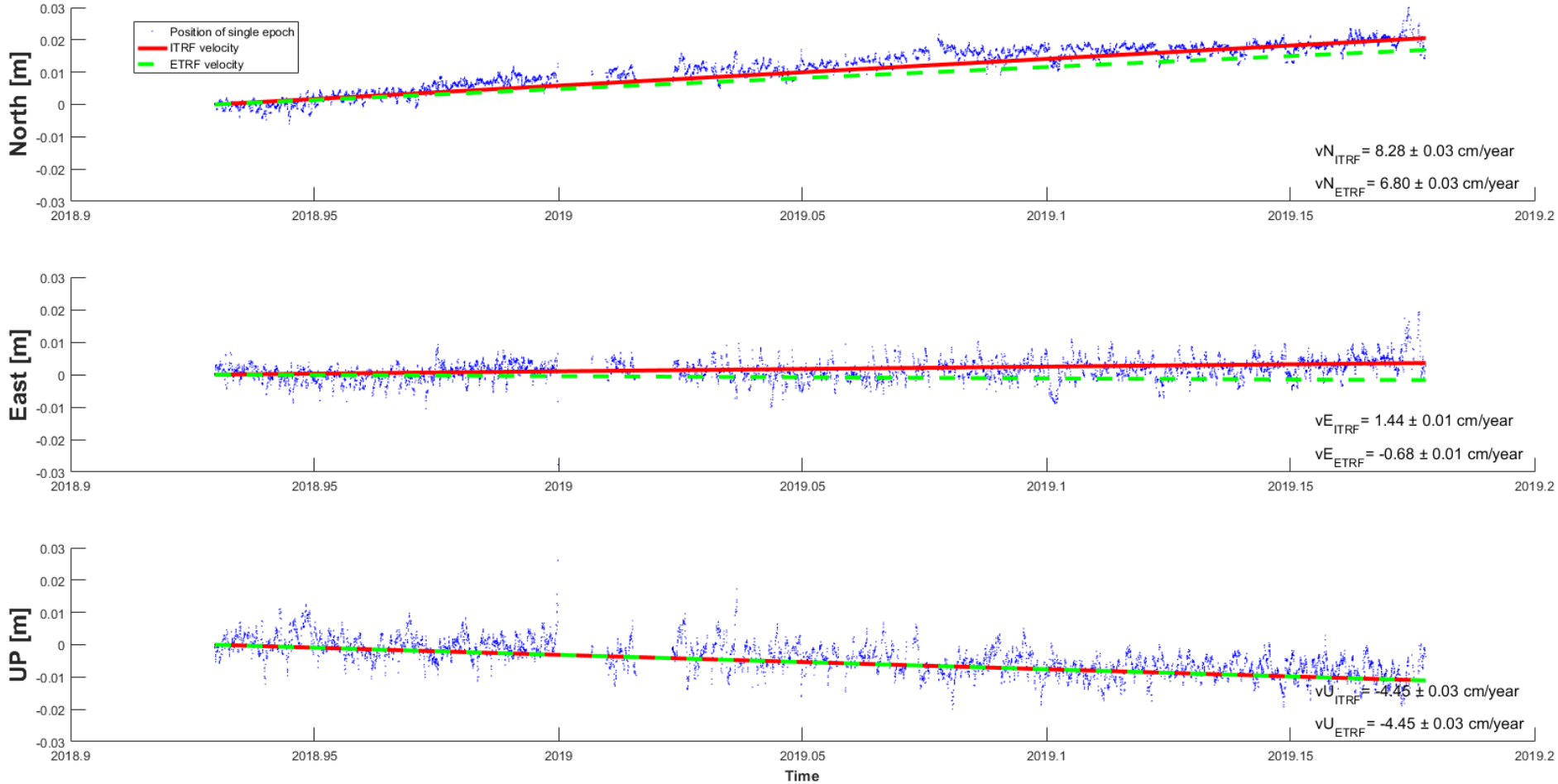
Low : -203.971 [mm]





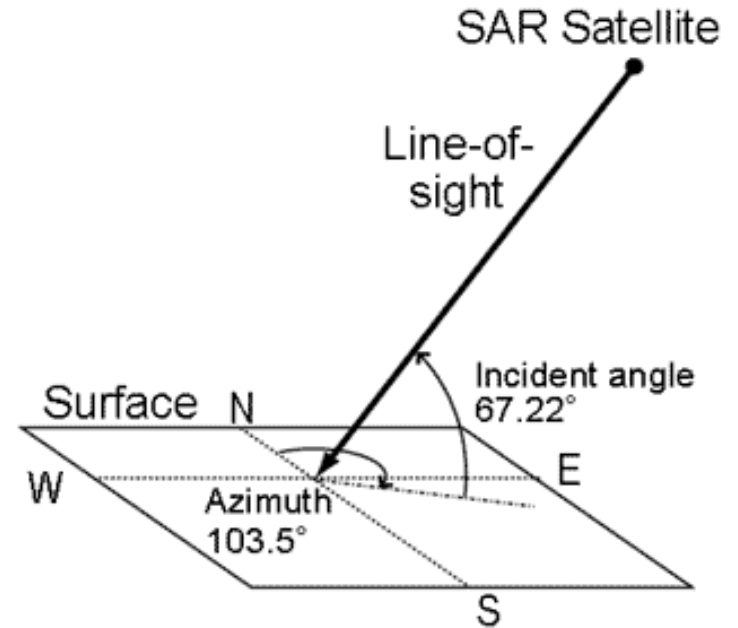
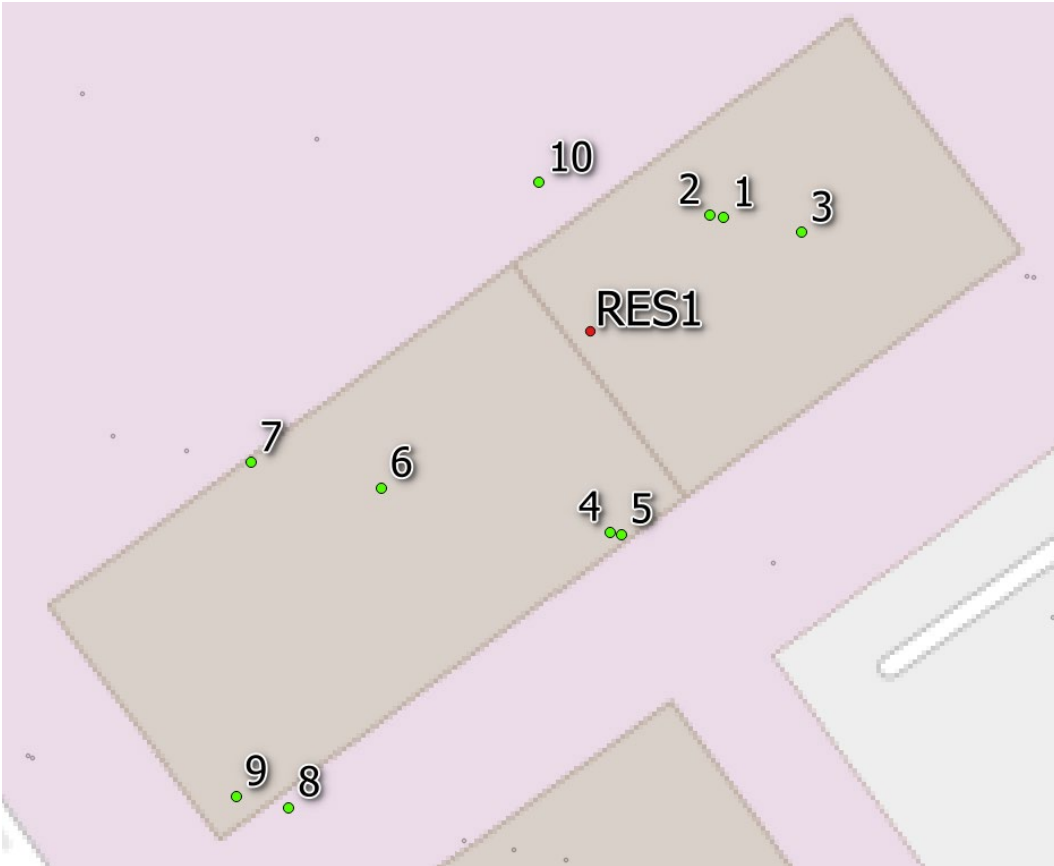
# The RES1 station

Station ID RES1





# Mining deformation of PInSAR



$$Z_{\text{los}} = [\sin(\theta_{\text{inc}}) \sin(\alpha) - \sin(\theta_{\text{inc}}) \cos(\alpha) \cos(\theta_{\text{inc}})] \begin{bmatrix} Z_n \\ Z_e \\ Z_u \end{bmatrix}$$



# Mining deformation of InSAR

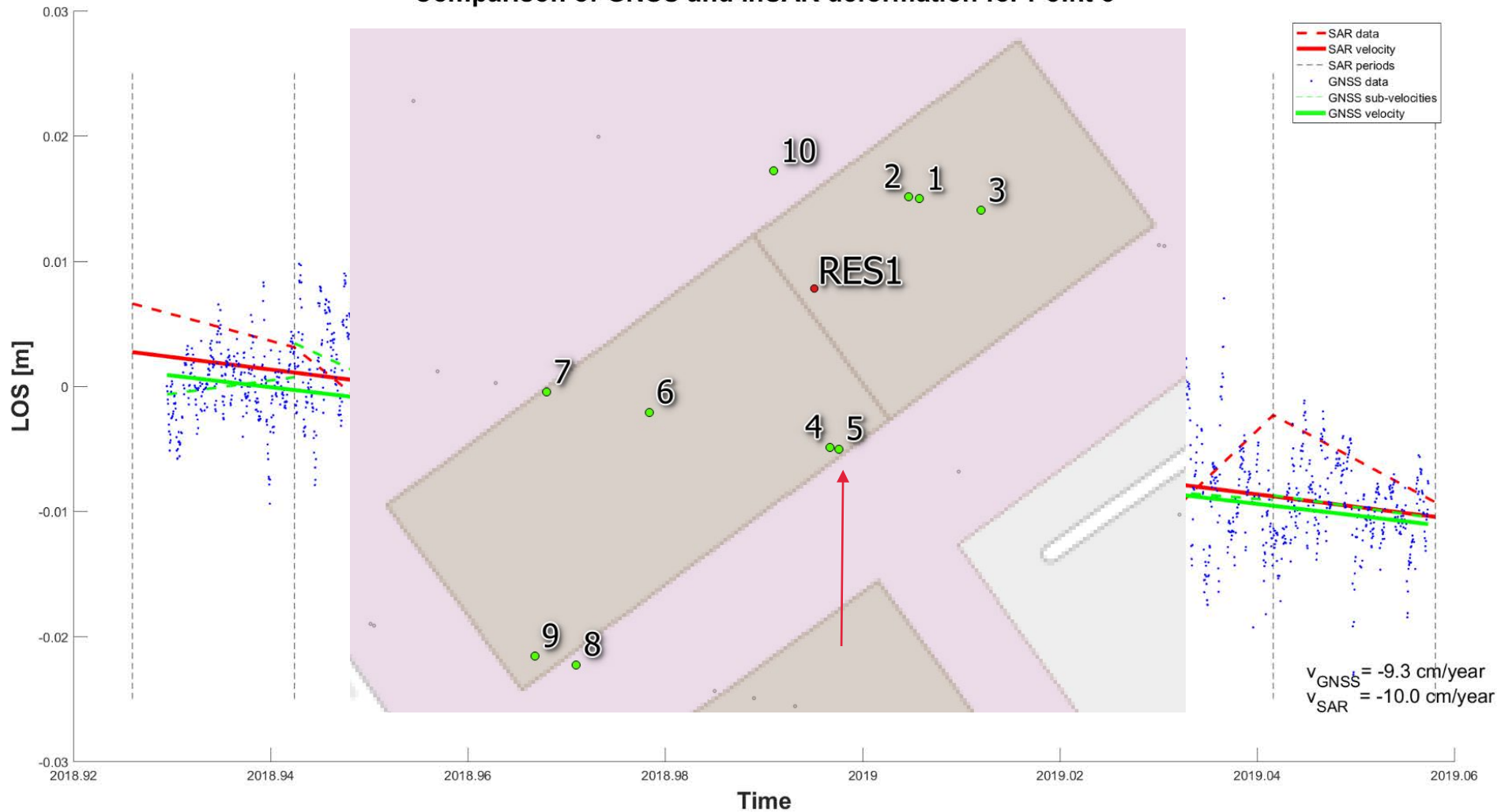
Comparison of GNSS and InSAR deformation for Point 10





# Mining deformation of PInSAR

## Comparison of GNSS and InSAR deformation for Point 5



# THANK YOU FOR ATTENTION

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